

Final Event 21 / 22 November 2023

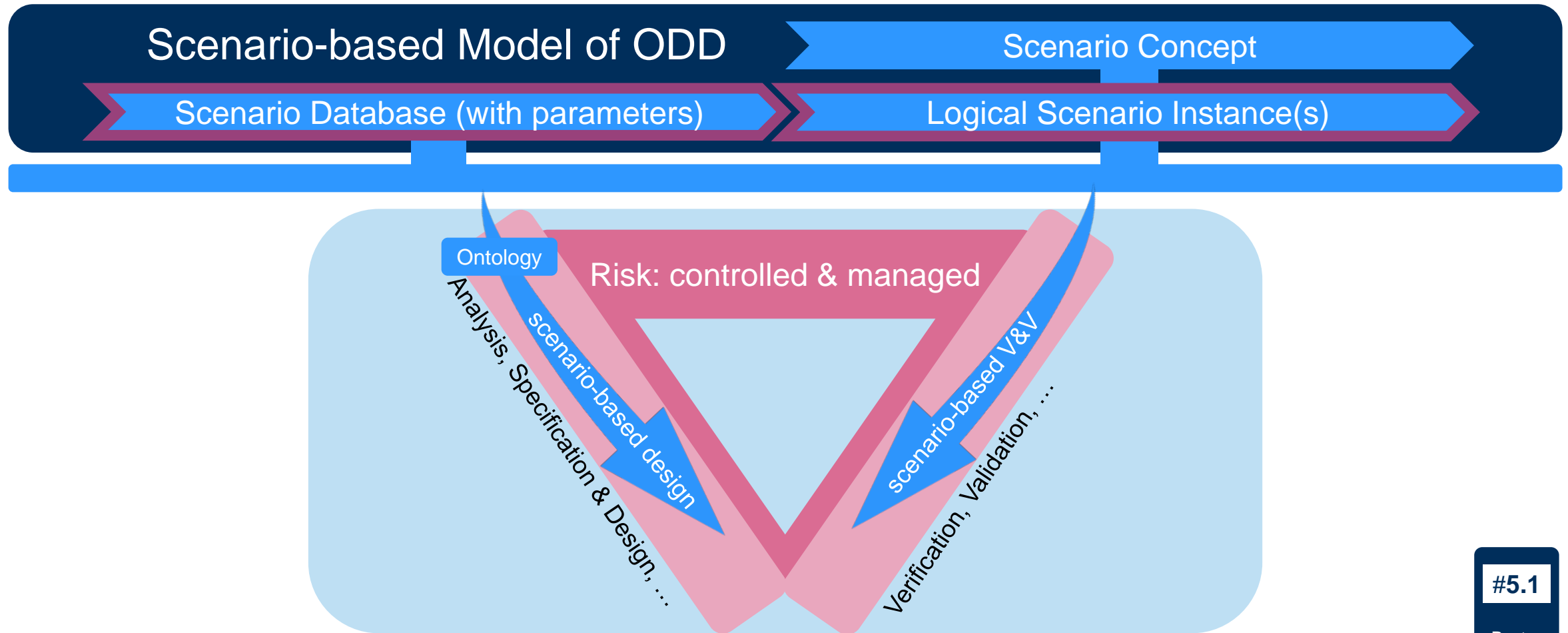
# Demonstrator: Scenario Database

Michael Schuldes, ika – RWTH Aachen

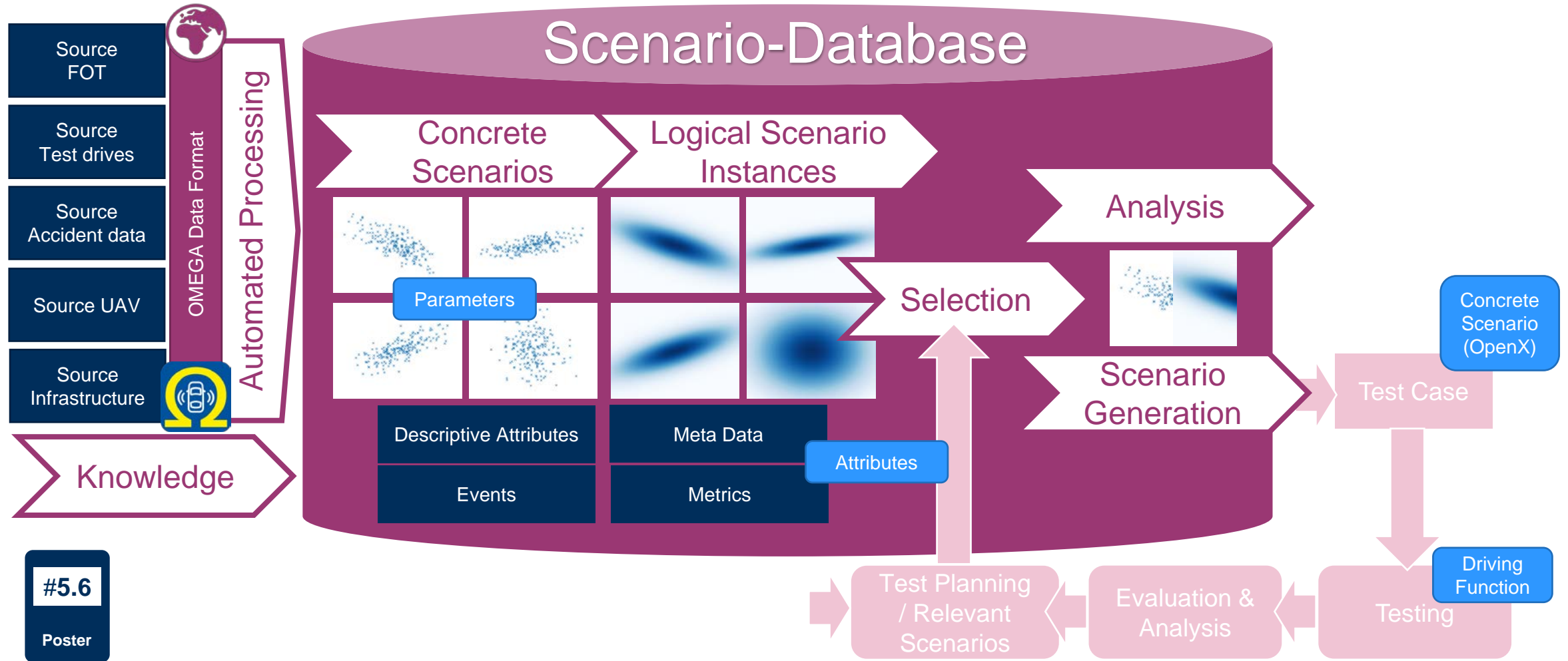
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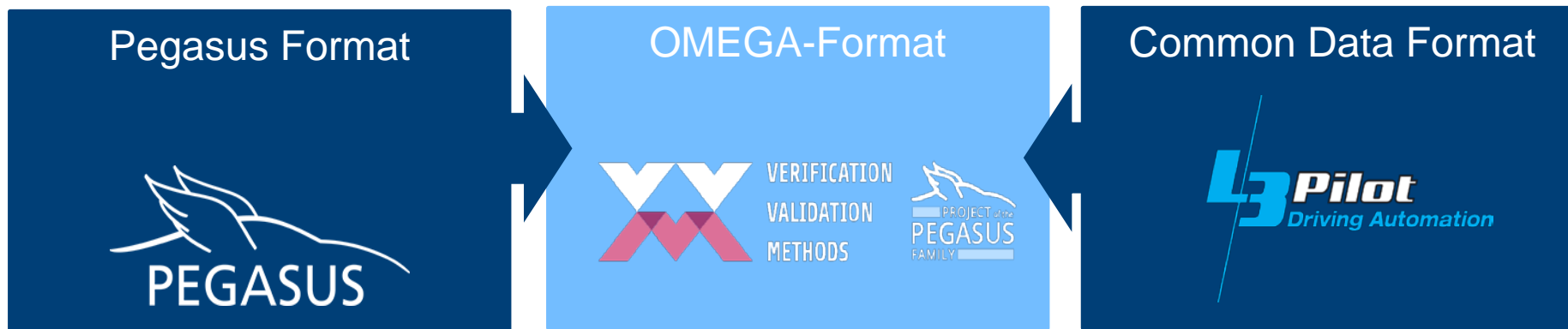
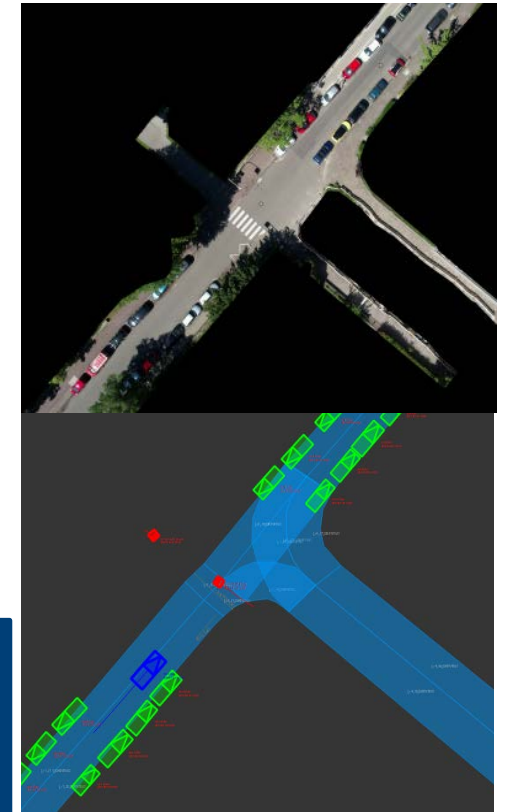
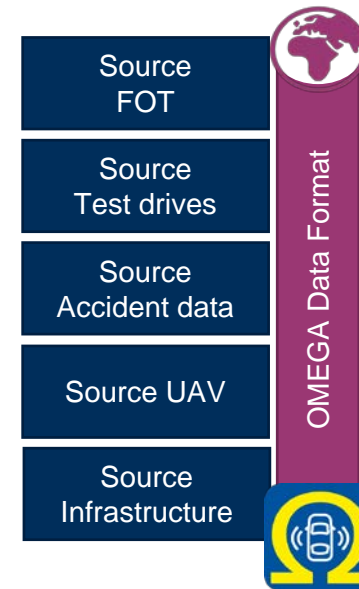
# Insight View of Scenario Databases



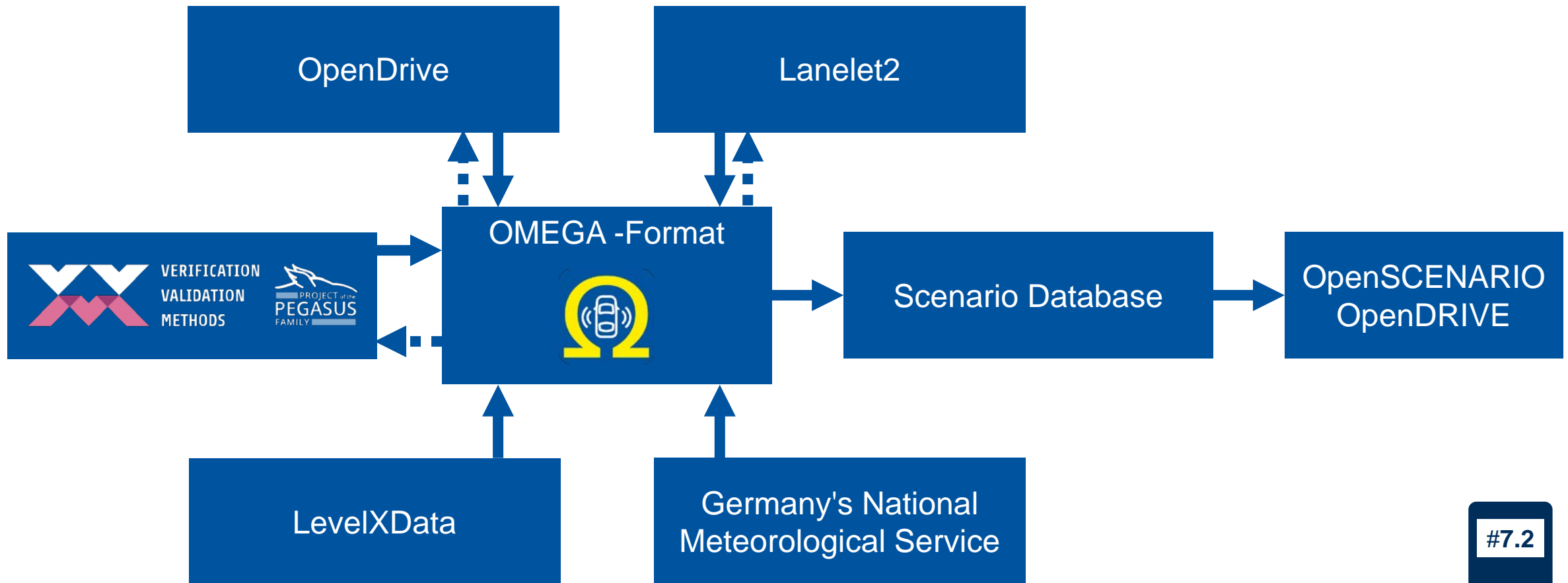
#5.6  
Poster

# Data: Omega Format

- → Diverse Data Needed: Combining Different Data Sources
- Data Format realizing 6-Layer Model and A.U.T.O. Ontology
- Unifying Map and Object-list based Trajectory Data in a hierarchical Format
- Enabling automated algorithms for scenario extraction
- Exchanged with a working group of UN ECE 157

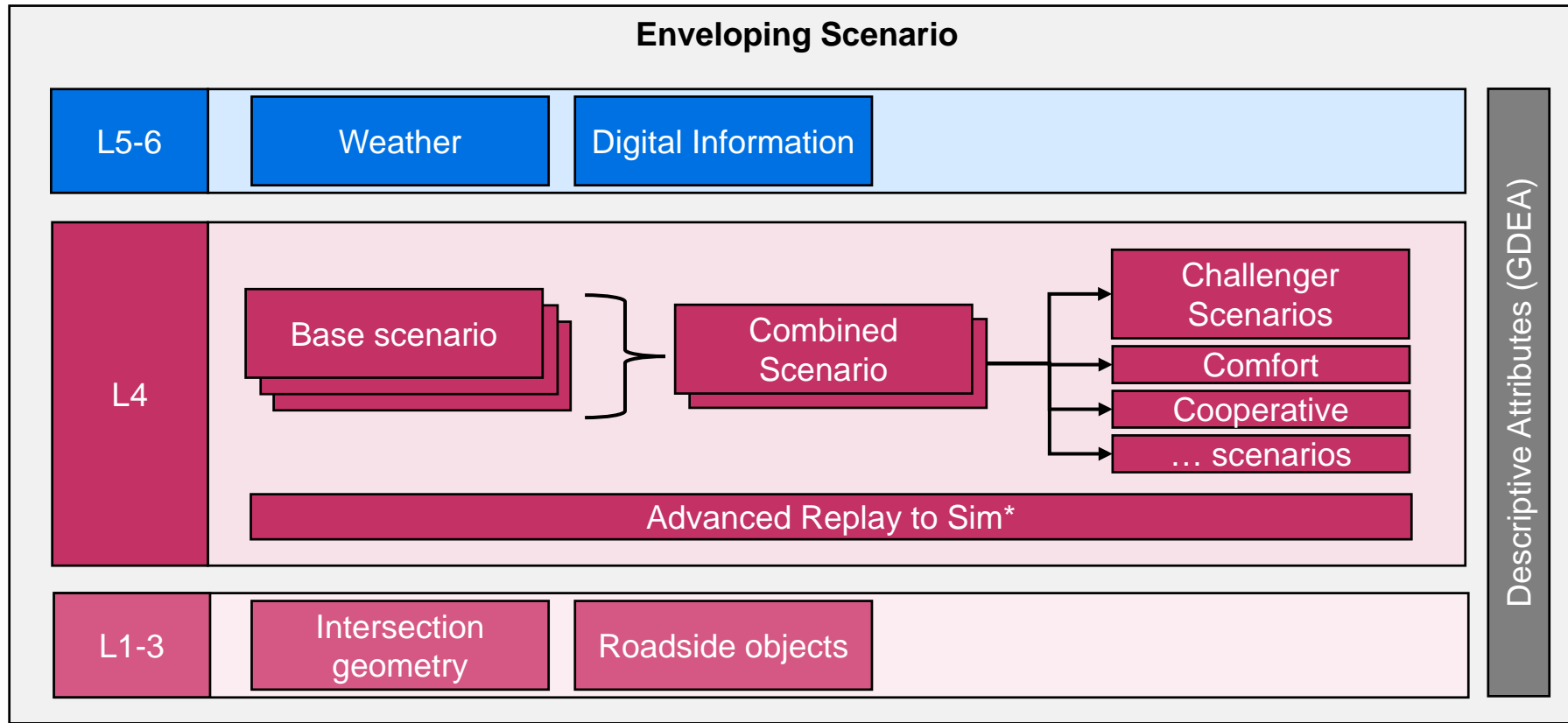


# Omega Format - Converters to and from Established Formats



# Scenario Concept to Structure Traffic

- ▶ Scenario concept to structure traffic area
- ▶ Base Scenarios encompass the ODD (realization of core scenarios)

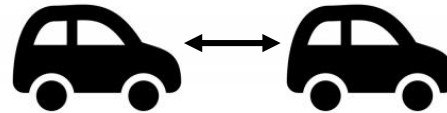


- ▶ Holistic Driving Scenario Concept for Urban Traffic
- ▶ Concepts describing abstract characteristics of traffic
- ▶ Combination of concepts defines base scenario



Individual concepts

- *Road user type*
- Intersection maneuver



Bilateral concepts

- Intersection conflict
- Longitudinal state
- Relative direction
- Traffic area change

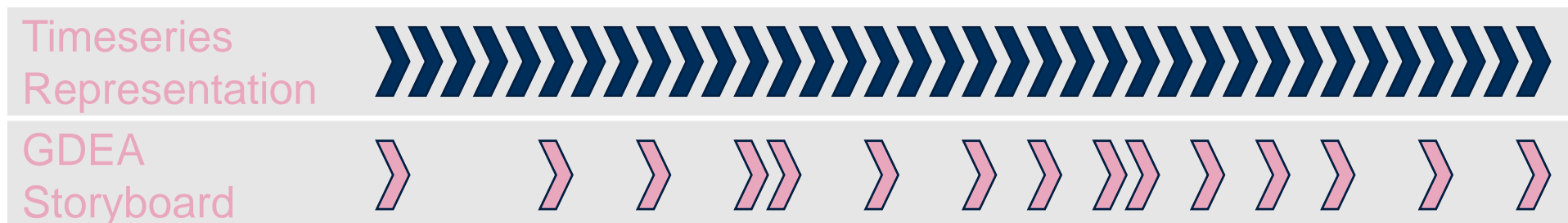
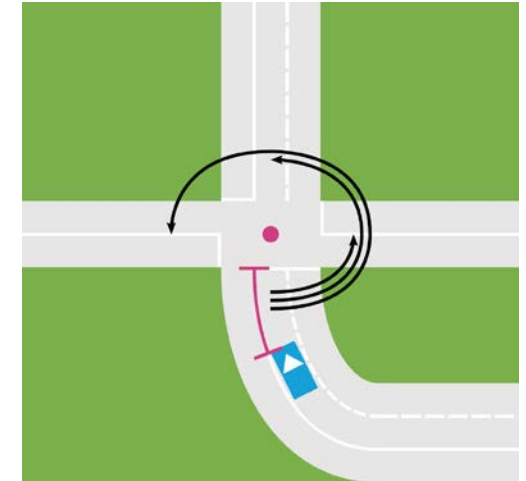


Global concepts

- *Traffic flow*
- *Traffic type*

# General Descriptive Entity Attributes (GDEA)

- ▶ Goal: Enable granular search beyond scenario definition
- ▶ Abstract ex-post description from the perspective of an entity (ego)
  - ▶ Complete trajectories are considered known
  - ▶ Representation of a “Reference”
- ▶ Abstraction of time series as a sequence of events (storyboard)
  - ▶ Occlusion (entering the field of vision of ego)
  - ▶ Passing of object
  - ▶ lane change
  - ▶ ...





# Scenario Identification and Attribute Calculation

- ▶ Explicit Knowledge
  - ▶ 6-Layer Model
  - ▶ The Automotive Urban Traffic Ontology
  - ▶ Holistic Urban Driving Scenario Ontology
- ▶ Identify Scenarios and their Parameters
- ▶ Attributes:
  - ▶ Infrastructure Abstraction
  - ▶ Metrics
    - ▶ Occlusion
    - ▶ TTC, THW, PET, ...
    - ▶ Dynamics Statistics

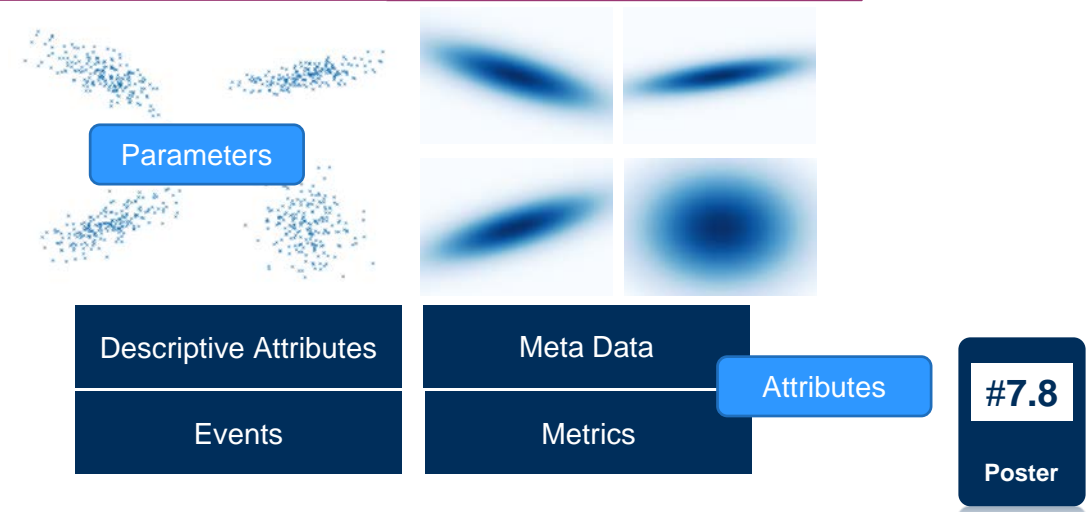
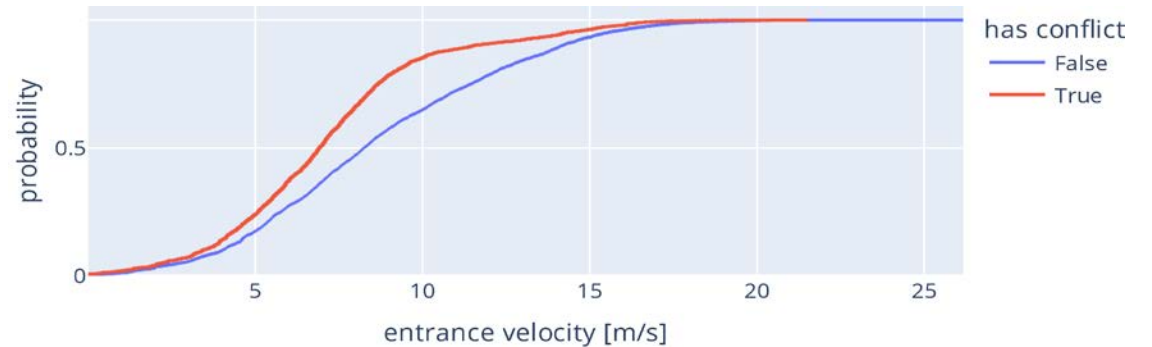
The top part of the image shows a top-down view of a traffic intersection. A red car is moving from left to right, and a blue car is moving from right to left. Labels indicate scenarios: 'Passing an oncoming object left' (pink), 'Pass straight with object crossing ego-traffic area from right before the node' (pink), 'Passing an object right' (blue), and 'Passing an object right' (blue).

The bottom part is a screenshot of an ontology editor (OntoGraf). The left pane shows a class hierarchy for 'Left turn approaching a leading object'. The right pane shows the details for this class, including annotations in English and German, a description, and a list of sub-classes and axioms.



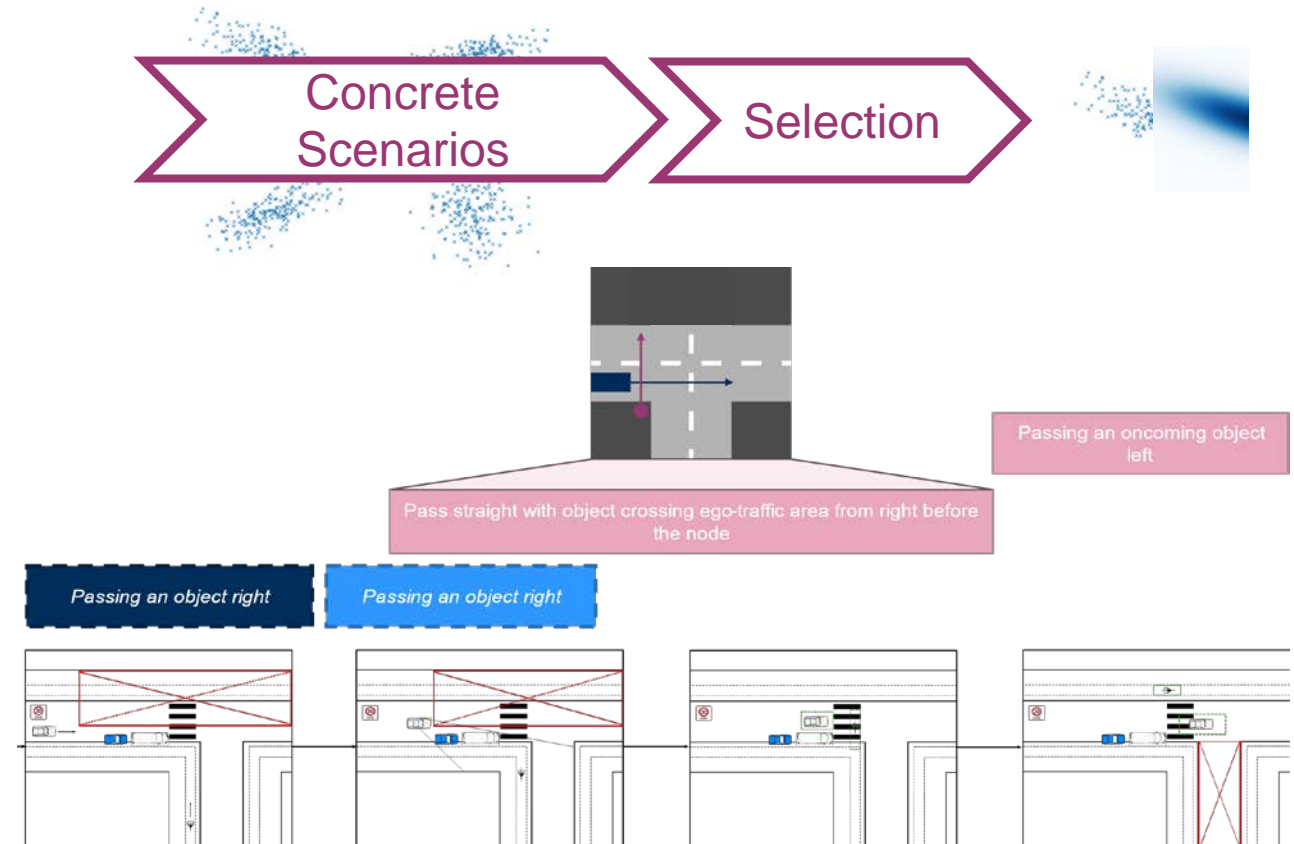
# Scenario Database – Understand the Data

- ▶ Collection of concrete scenario
  - ▶ Logical scenarios with distributions
- ▶ Analyze available data
  - ▶ Estimating Occurrence Probability
  - ▶ Distribution of interaction partners
  - ▶ Parameter Distributions
  - ▶ ...

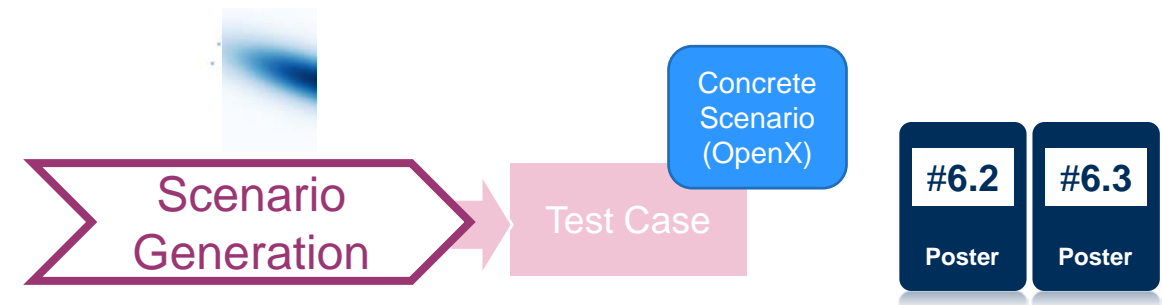


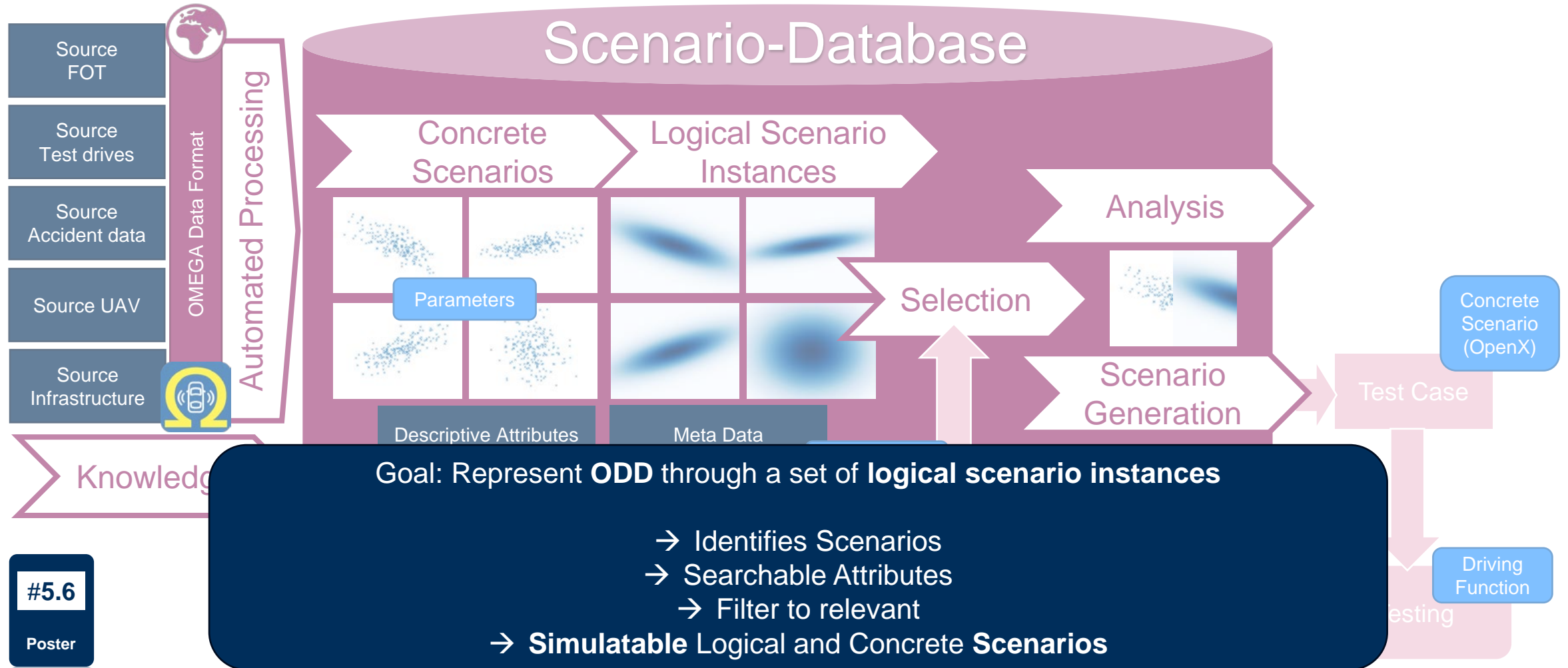
# Selection of Subset of ODD – Database Filtering

- ▶ Fine-grained selection of scenarios
- ▶ Based on Attributes and Parameters
- ▶ Type of Base Scenario
- ▶ Parameter Range
  - ▶ TTC range
  - ▶ Precipitation
  - ▶ Number of intersection arms
- ▶ Sequence of Scenarios
  - ▶ Define Sequence through query graph



- ▶ Acquire concrete scenarios from logical scenario instances
- ▶ Directly use concrete scenarios
- ▶ Different Levels of Abstraction
  - ▶ Replay to Sim
  - ▶ Advanced Replay to Sim
  - ▶ Base Scenario
  - ▶ Combined Scenarios (Sequence of Base Scenarios)
- ▶ Target Output: ASAM OpenSCENARIO/DRIVE
  - ▶ OpenPASS
  - ▶ esmini





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Poster

# Thank you!

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A project developed by the VDA Leitinitiative  
autonomous and connected driving

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- [1] M. Scholtes, L. Westhofen, L. Turner, K. Lotto, M. Schuldes, H. Weber, N. Wagener, C. Neurohr, M. Bollmann, F. Körte, J. Hiller, M. Hoss, J. Bock, and L. Eckstein „6-Layer Model for a Structured Description and Categorization of Urban Traffic and Environment“, IEEE Access, 2021.
- [2] H. Weber, C. Glasmacher, M. Schuldes, N. Wagener, and L. Eckstein „Holistic Driving Scenario Concept for Urban Traffic“, IEEE Intelligent Vehicles Symposium, 2023.
- [3] C. Glasmacher, H. Weber, M. Schuldes, N. Wagener, and L. Eckstein „Generation of Concrete Parameters from Logical Urban Driving Scenarios Based on Hybrid Graphs“, VEHITS, 2023.
- [4] C. Glasmacher, M. Schuldes, H. Weber, N. Wagener, and L. Eckstein „Acquire Driving Scenarios Efficiently: A Framework for Prospective Assessment of Cost-Optimal Scenario Acquisition“, IEEE Intelligent Transportation Systems Conference, 2023.
- [5] M. Scholtes, M.Schuldes, H. Weber, N. Wagener, M. Hoss and L.Eckstein „OMEGAFormat: A Comprehensive Format of Traffic Recordings for Scenario Extraction“, Uni-DAS FAS Workshop, 2022.