ODD based Safety Assurance for Automated Driving Systems: Standards and tools

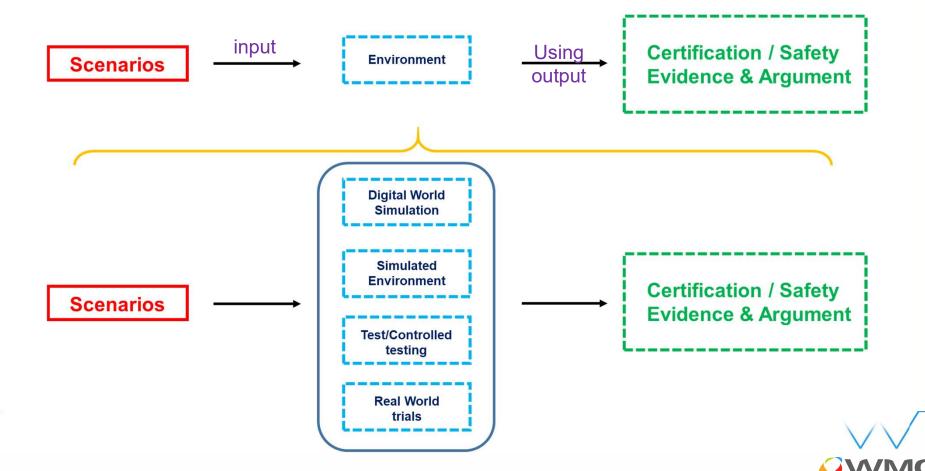
Dr Siddartha Khastgir CEng MIMechE Head of Verification & Validation, Intelligent Vehicles WMG, University of Warwick, UK



VVM Mid-Term Event 16 March 2022





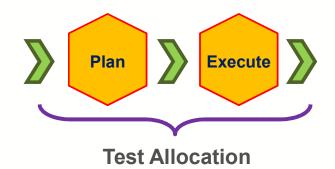


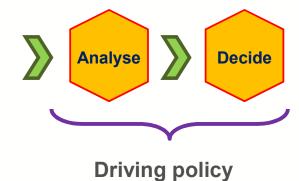
Scenarios





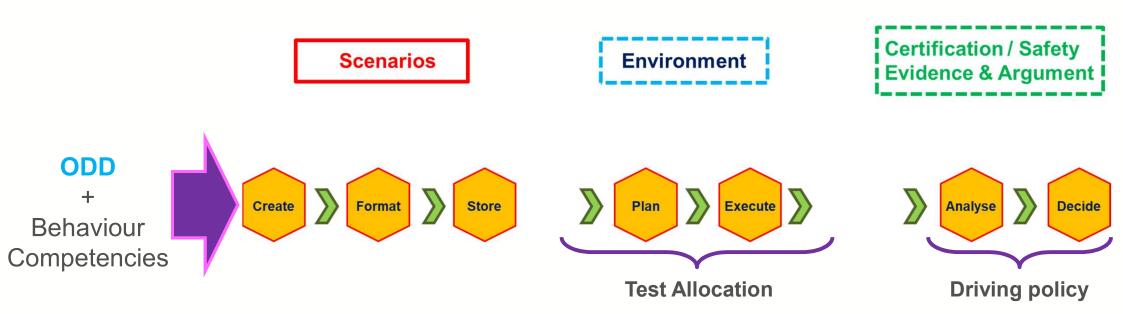






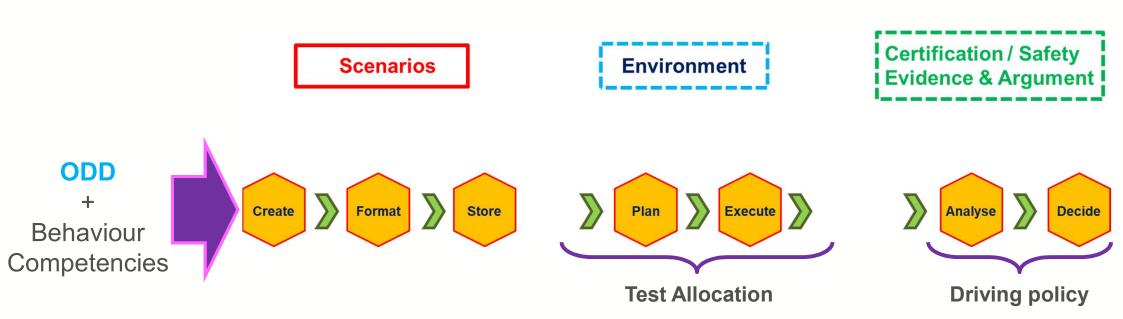


ODD based Scalable Safety Assurance Framework



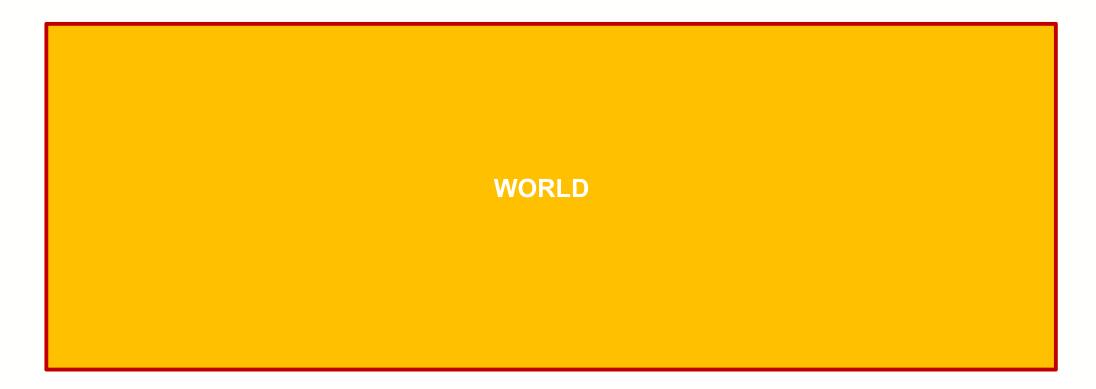


ODD based Scalable Safety Assurance Framework

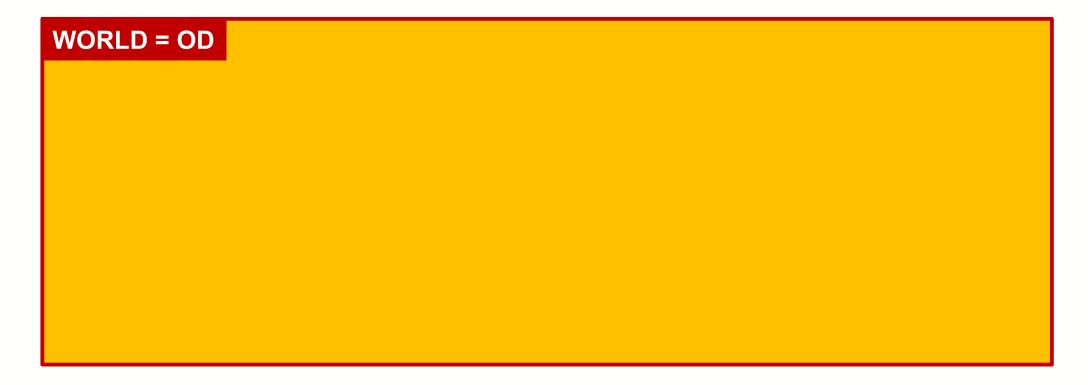


Standards and Tools!

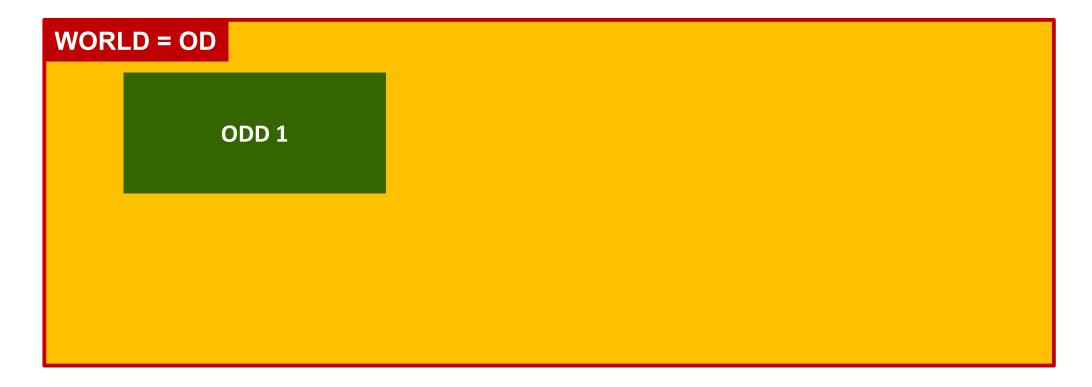




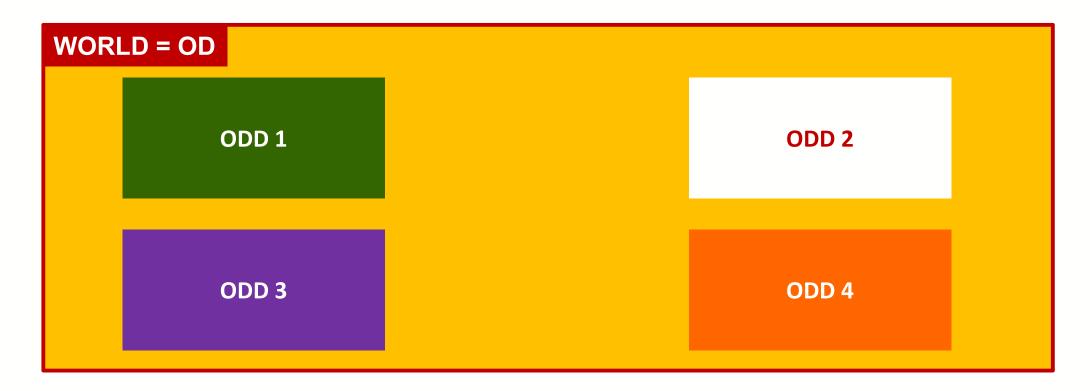












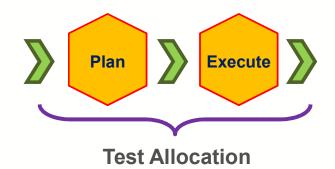


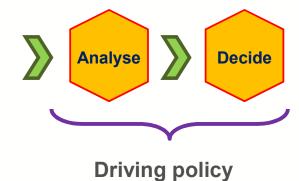
Scenarios













Scenarios









Analyse

Test Allocation

Driving policy

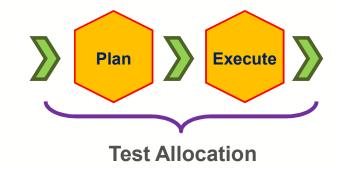


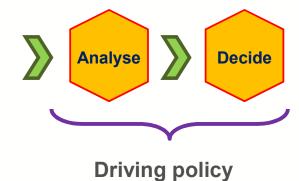
Scenarios

Environment

Certification / Safety
Evidence & Argument

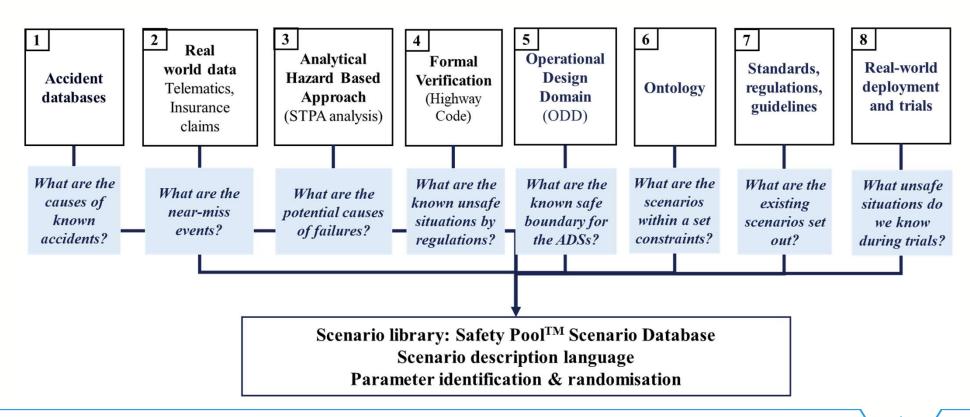






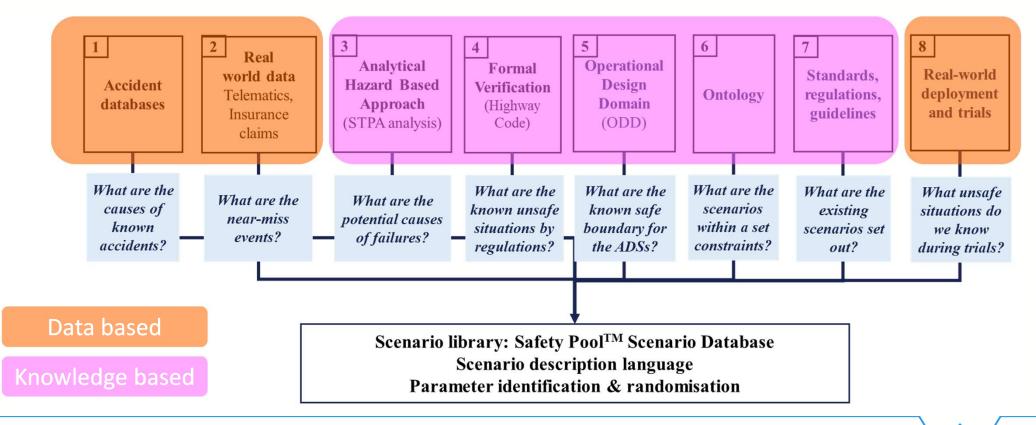


Scenarios





Scenarios



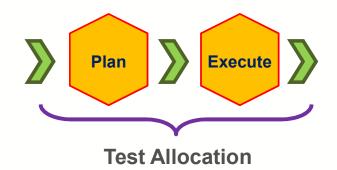


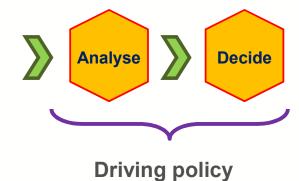
Scenarios

Environment

Certification / Safety
Evidence & Argument













Q Scenarios

Libraries

Test Suites

• Testbeds

Users

Roles

Settings

■ Audit Log

WMG



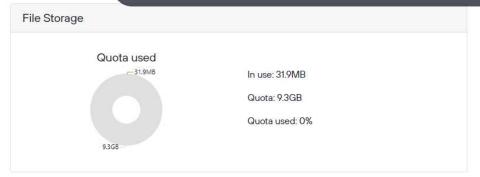
Welcome

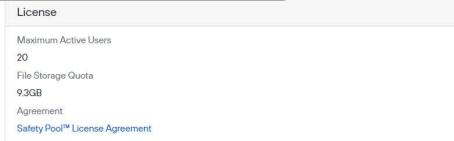
The Safety Pool Database is an extensive collection of curated test scenarios which can be used for testing connected and autonomous driving technologies.

Learn more

Safety PoolTM Scenario Database

World's Largest Public Scenario Database









Q Scenarios

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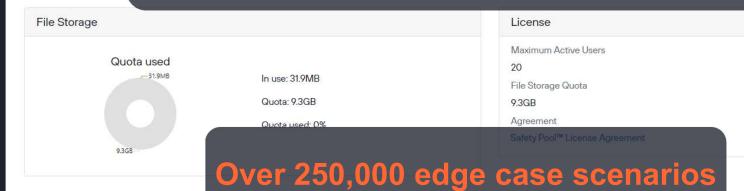
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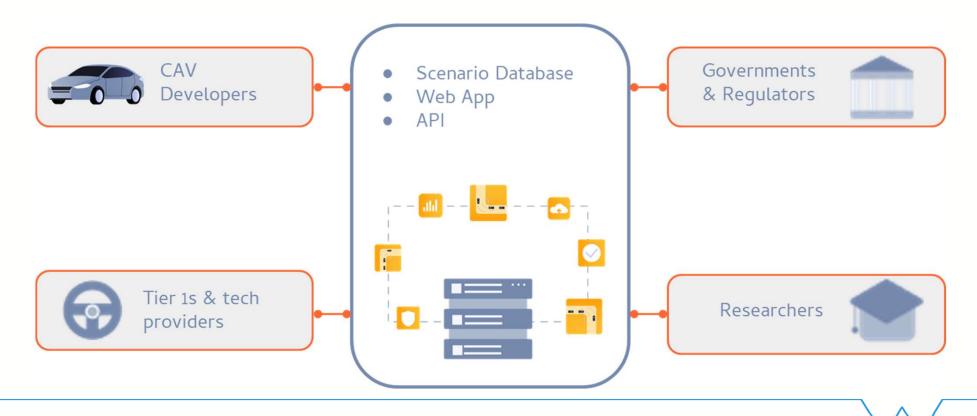
Safety PoolTM Scenario Database

World's Largest Public Scenario Database



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What is the Safety PoolTM Scenario Database?





WMG



A Home

Q Scenarios

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Audit Log

← Scenario

Download

Add to Test Suite

stat19_1_82482

Tags Definition Files Route Locations Versions

Scenery

- Broken line
- Contaminated
- Drive on left
- Lane dimensions [Width (m): 3.4 to 3.7]
- Level plane
- Normal roundabout
- Number of lanes [Lanes: 2]

Environmental Conditions

- Cloudiness [Cloud cover (okta): 0 to 1]
- Day
- Sun elevation [Angle (degree): 10 to 30]

Agents

- Cut-in
- Lane change left

Meta Data

Fatal collision

- Radial road
- Shoulder (grass)
- Straights
- Traffic lane
- Undivided road
- Uniform surface
- Sun to the right
- Wind [Speed (m/s): 10.8 to 13.8]

Vehicle

General



URN

d025e967-a9eb-452e-bd13-af66ec99a318

Library

STATS-19

License 0

Safety Pool™ Test Script License

Version

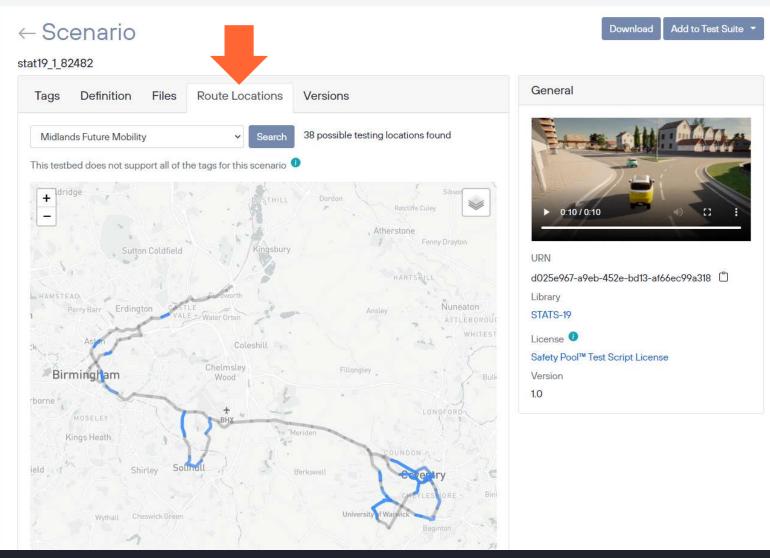
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- ♠ Home
- Q Scenarios
- Libraries
- Test Suites
- Testbeds
- Users
- Roles
- Settings
- Audit Log

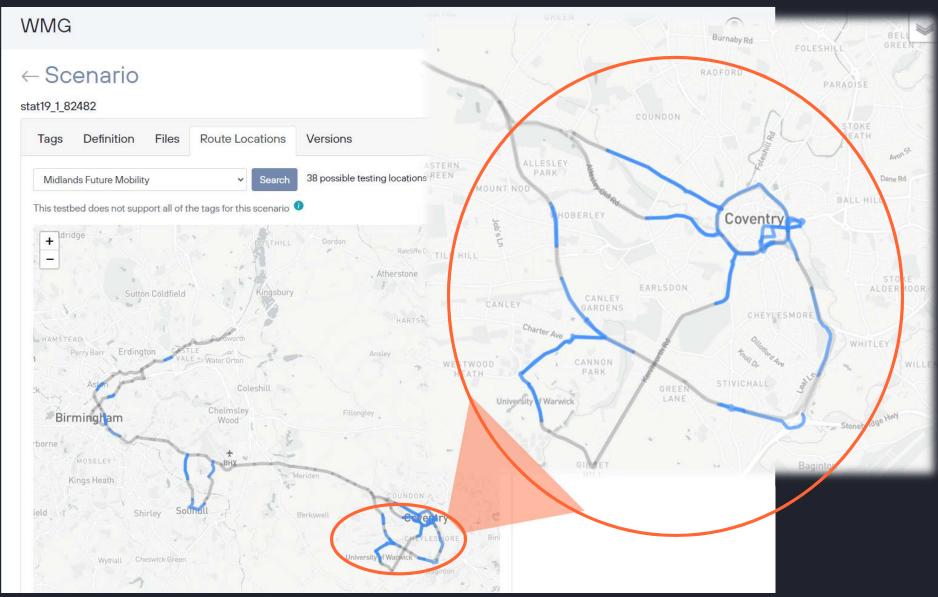
WMG







- A Home
- Q Scenarios
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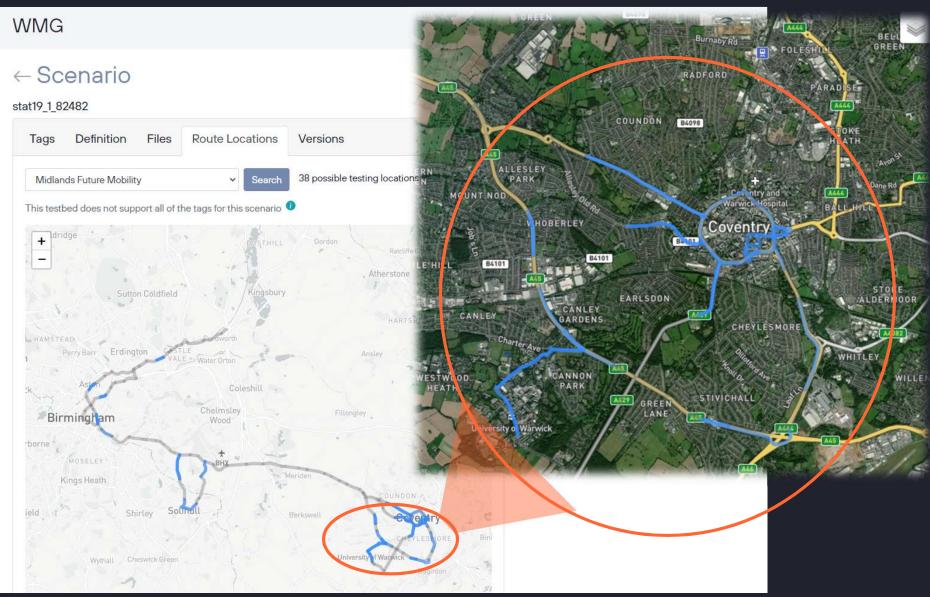


☑ Testbeds☑ Users

Roles

Settings

■ Audit Log



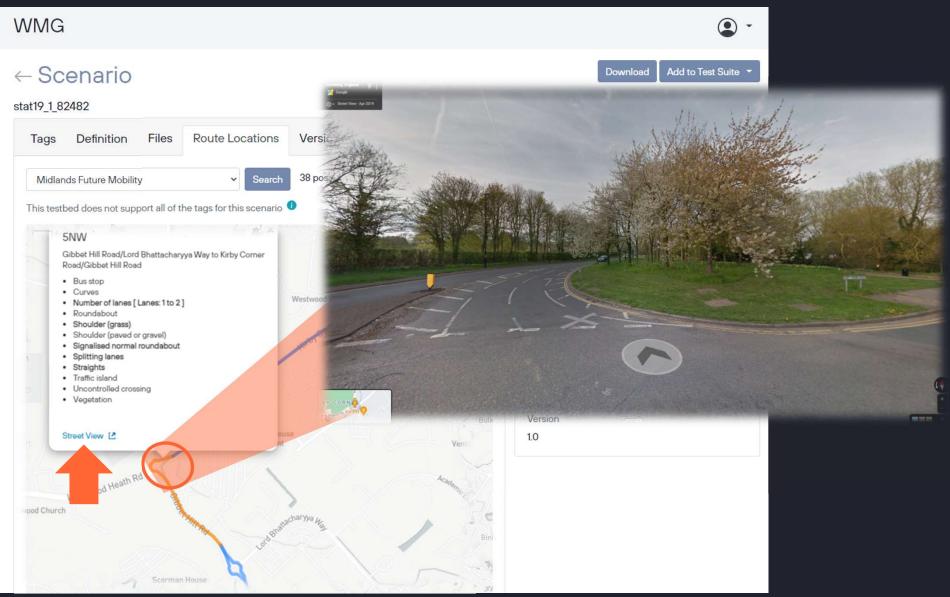


☑ Testbeds☑ Users

Noles

Settings

■ Audit Log

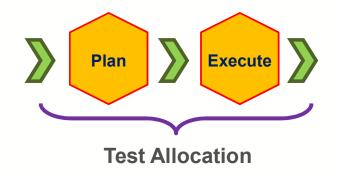


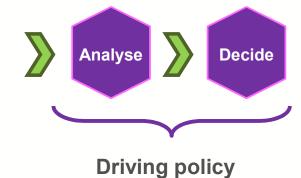
Scenarios

Environment

Certification / Safety
Evidence & Argument









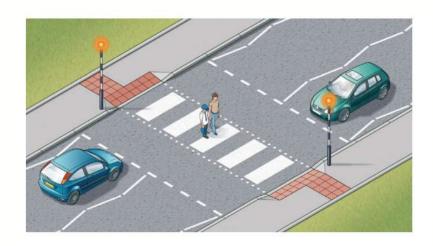
Rules of the Road (for human drivers)

- UK Highway code (for human drivers) rule defines:
 - Doing some behaviour somewhere
 - NOT doing some behaviour somewhere
- Doing/not doing: Behaviour competency library
- Somewhere: ODD instantiation



UK Highway Code: Rule 195

"As you approach a zebra crossing: look out for pedestrians waiting to cross and be ready to slow down or stop to let them cross; you MUST give way when a pedestrian has moved onto a crossing"



Rule 19: Zebra crossings have flashing beacons

Behaviour

ODD



UK Highway Code: Rule 195

"As you approach a zebra crossing: look out for pedestrians waiting to cross and be ready to slow down or stop to let them cross; you MUST give way when a pedestrian has moved onto a crossing"



Rule 19: Zebra crossings have flashing beacons

How long to wait?

Behaviour

ODD

Assumptions



ODD based Codified Rules of the Road

Current Rules of Road (for human drivers) = f(Operating condition, Behaviour competency, Assumptions)



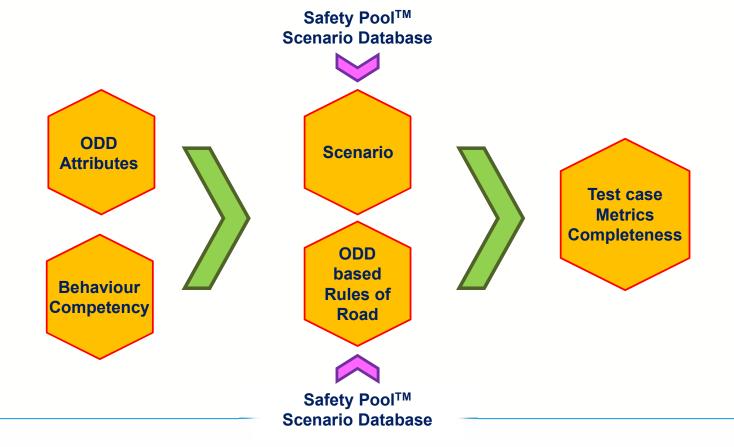
Codified Rule of the Road

= f(Operating condition, behaviour competency, driving characteristics)



IMPLICATIONS

ODD based Scalable Safety Assurance Framework





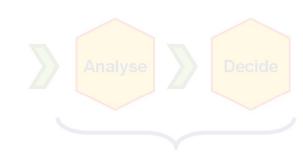
Scenarios





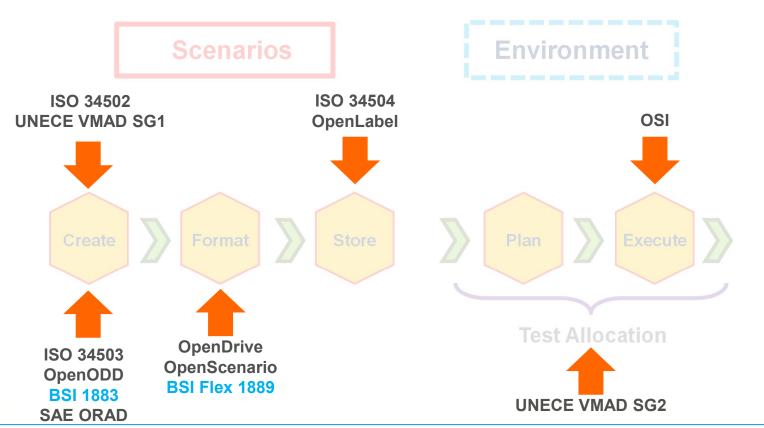


Test Allocation



Driving policy

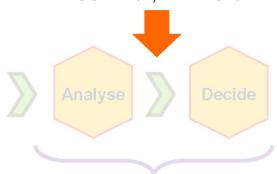




STANDARDS REGULATIONS

Evidence & Argument

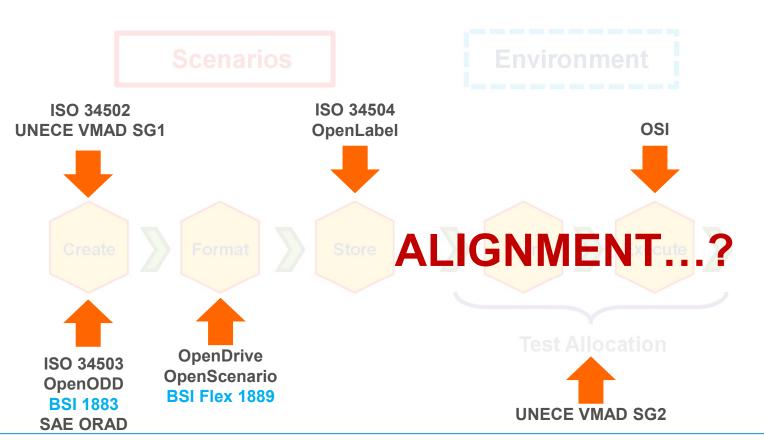
ISO 21448, ISO TS 5083 ISO 21434, IEEE 2846



Driving policy



REGULATIONS





ISO 21448, ISO TS 5083 ISO 21434, IEEE 2846

STANDARDS





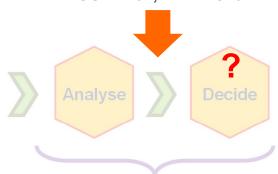
Scenarios Environment ISO 34502 UNECE VMAD SG1 OpenLabel Oreate Format OpenDrive OpenScenario OpenScenario

UNECE VMAD SG2

STANDARDS REGULATIONS

Certification / Safety
Evidence & Argument

ISO 21448, ISO TS 5083 ISO 21434, IEEE 2846



Driving policy



BSI 1883

SAE ORAD

BSI Flex 1889

Summary

Each aspect of safety assurance of Automated Driving Systems needs to consider its **relationship with ODD**.

Scenarios need to be a function of their ODD. Safety metrics need to be a function of ODD.

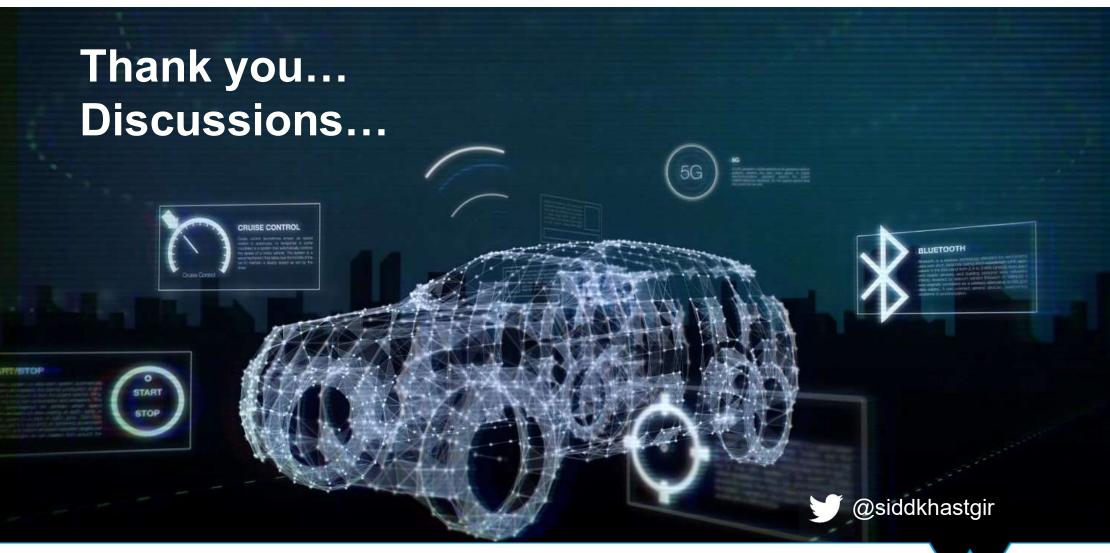
Need for **concrete tools and methods** to convert philosophical concepts into implementation.

Focus on **addressing gaps in standards** and consolidation of existing standards.

Success will be dependent upon suitable collaboration and data sharing, nationally and internationally.







Dr Siddartha Khastgir CEng MIMechE S.Khastgir.1@warwick.ac.uk

